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Sensor Fusion for Targets Detection using LLM-based Transfer Learning Approach

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17 June 2025, 13:30PM via Zoom

https://tau-ac-il.zoom.us/j/83251482591?pwd=eEZ27bp3nZXXvyiyht5oknrJ2w5Vye.1

Abstract:

Sensor fusion of LIDAR and optical data is essential for reliable target detection in autonomous vehicles, yet classical methods struggle to model the complex physical relationships between them. A new method for combining spatial data is presented that uses a Large Language Model (LLM) with Transfer Learning approach, taking advantage of its knowledge from language tasks to accomplish the task of spatial data fusion. The model's objective is to generate a more accurate and unified global target map by leveraging the contextual understanding capabilities of the transformer architecture for data fusion.

Bio:

Yuval Ziv is a M.Sc student at the School of Industrial Engineering and Intelligent Systems at Tel Aviv University. He is conducting his research under Prof. Irad Ben-Gal and Dr. Barouch Matzliach. In addition, he works as a Data Scientist at CB4, a subsidiary of GAP.